Chapter 5: Propositions and Inference

- An interpretation is an assignment of values to all variables.
- A model is an interpretation that satisfies the constraints.
- Often we don't want to just find a model, but want to know what is true in all models.
- A proposition is statement that is true or false in each interpretation.

- Specifying logical formulae is often more natural than filling in tables
- It is easier to check correctness and debug formulae than tables
- We can exploit the Boolean nature for efficient reasoning
- We need a language for asking queries (of what follows in all models) that may be more complicated than asking for the value of a variable
- It is easy to incrementally add formulae
- It can be extended to infinitely many variables with infinite domains (using logical quantification)

Step 1 Begin with a task domain.

Step 2 Choose atoms in the computer to denote propositions. These atoms have meaning to the KB designer.

Step 3 Tell the system knowledge about the domain.

Step 4 Ask the system questions.

— the system can tell you whether the question is a logical consequence.

- You can interpret the answer with the meaning associated with the atoms.

In computer:

In user's mind:

- *light1_broken*: light #1 is broken
- *sw_up*: switch is up
- *power*: there is power in the building
- *unlit_light*1: light #1 isn't lit
- *lit_light*2: light #2 is lit

Conclusion: *light1_broken*

- The computer doesn't know the meaning of the symbols
- The user can interpret the symbol using their meaning

- An atom is a symbol starting with a lower case letter
- A body is an atom or is of the form $b_1 \wedge b_2$ where b_1 and b_2 are bodies.
- A definite clause is an atom or is a rule of the form $h \leftarrow b$ where h is an atom and b is a body.
- A knowledge base is a set of definite clauses

- An interpretation / assigns a truth value to each atom.
- A body $b_1 \wedge b_2$ is true in I if b_1 is true in I and b_2 is true in I.
- A rule h ← b is false in I if b is true in I and h is false in I. The rule is true otherwise.
- A knowledge base *KB* is true in *I* if and only if every clause in *KB* is true in *I*.

- A model of a set of clauses is an interpretation in which all the clauses are *true*.
- If KB is a set of clauses and g is a conjunction of atoms, g is a logical consequence of KB, written $KB \models g$, if g is true in every model of KB.
- That is, $KB \models g$ if there is no interpretation in which KB is *true* and g is *false*.

$$\mathcal{KB} = \left\{ egin{array}{c} p \leftarrow q. \\ q. \\ r \leftarrow s. \end{array}
ight.$$

	р	q	r	S	model?
I_1	true	true	true	true	
I_2	false	false	false	false	
I_3	true	true	false	false	
I_4	true	true	true	false	
I_5	true	true	false	true	

$$\mathcal{KB} = \left\{ egin{array}{c} p \leftarrow q. \\ q. \\ r \leftarrow s. \end{array}
ight.$$

	р	q	r	5
I_1	true	true	true	true
I_2	false	false	false	false
I_3	true	true	false	false
<i>I</i> 4	true	true	true	false
I_5	true	true	false	true

model? is a model of *KB* not a model of *KB* is a model of *KB* is a model of *KB* not a model of *KB*

$$\mathcal{KB} = \left\{ egin{array}{c} p \leftarrow q, \\ q, \\ r \leftarrow s. \end{array}
ight.$$

	р	q	r	S	model?
I_1	true	true	true	true	is a model of <i>KB</i>
I_2	false	false	false	false	not a model of <i>KB</i>
I_3	true	true	false	false	is a model of <i>KB</i>
<i>I</i> 4	true	true	true	false	is a model of <i>KB</i>
I_5	true	true	false	true	not a model of <i>KB</i>

Which of p, q, r, q logically follow from KB?

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$$\mathcal{K}B = \begin{cases} p \leftarrow q. \\ q. \\ r \leftarrow s. \end{cases}$$

	р	q	r	S	model?
I_1	true	true	true	true	is a model of <i>KB</i>
I_2	false	false	false	false	not a model of <i>KB</i>
I_3	true	true	false	false	is a model of <i>KB</i>
I_4	true	true	true	false	is a model of <i>KB</i>
I_5	true	true	false	true	not a model of <i>KB</i>

Which of p, q, r, q logically follow from KB? $KB \models p, KB \models q, KB \not\models r, KB \not\models s$

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- 1. Choose a task domain: intended interpretation.
- 2. Associate an atom with each proposition you want to represent.
- 3. Tell the system clauses that are true in the intended interpretation: axiomatizing the domain.
- 4. Ask questions about the intended interpretation.
- 5. If $KB \models g$, then g must be true in the intended interpretation.
- 6. Users can interpret the answer using their intended interpretation of the symbols.

- The computer doesn't have access to the intended interpretation.
- All it knows is the knowledge base.
- The computer can determine if a formula is a logical consequence of KB.
- If $KB \models g$ then g must be true in the intended interpretation.
- If $KB \not\models g$ then there is a model of KB in which g is false. This could be the intended interpretation.

Electrical Environment



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Representing the Electrical Environment

light h	$lit_l_1 \leftarrow light_l_1 \land live_w_0 \land ok_l_1$
light la	$\mathit{live_w_0} \leftarrow \mathit{live_w_1} \land \mathit{up_s_2}.$
down c	$\mathit{live_w_0} \leftarrow \mathit{live_w_2} \land \mathit{down_s_2}.$
$uown_s_1$.	$\mathit{live_w_1} \leftarrow \mathit{live_w_3} \land \mathit{up_s_1}.$
up_{s_2} .	$\mathit{live_w_2} \leftarrow \mathit{live_w_3} \land \mathit{down_s_1}.$
up_s ₃ .	$lit_{l_2} \leftarrow light_{l_2} \wedge live_{w_4} \wedge ok_{l_2}$.
ok_l ₁ .	$live_{w_4} \leftarrow live_{w_3} \wedge up_{s_3}$.
ok_l ₂ .	$live_p_1 \leftarrow live_w_3$.
$ok_{-}cb_{1}$.	live $w_3 \leftarrow live w_5 \land ok cb_1$.
$ok_{-}cb_{2}$.	live $p_2 \leftarrow$ live w_6
live_outside.	live $w_c \leftarrow live w_c \land ok ch_c$
	$live_w_5 \leftarrow live_outside.$

- A proof is a mechanically derivable demonstration that a formula logically follows from a knowledge base.
- Given a proof procedure, $KB \vdash g$ means g can be derived from knowledge base KB.
- Recall $KB \models g$ means g is true in all models of KB.
- A proof procedure is sound if $KB \vdash g$ implies $KB \models g$.
- A proof procedure is complete if $KB \models g$ implies $KB \vdash g$.

One rule of derivation, a generalized form of modus ponens: If " $h \leftarrow b_1 \land \ldots \land b_m$ " is a clause in the knowledge base, and each b_i has been derived, then h can be derived.

This is forward chaining on this clause. (This rule also covers the case when m = 0.)

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 $KB \vdash g$ if $g \in C$ at the end of this procedure:

 $C := \{\};$

repeat

select clause " $h \leftarrow b_1 \land \ldots \land b_m$ " in *KB* such that $b_i \in C$ for all *i*, and $h \notin C$; $C := C \cup \{h\}$ until no more clauses can be selected.

 $a \leftarrow b \land c$. $a \leftarrow e \wedge f$. $b \leftarrow f \wedge k$. $c \leftarrow e$. $d \leftarrow k$. е. $f \leftarrow j \land e$. $f \leftarrow c$. $j \leftarrow c$.

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If $KB \vdash g$ then $KB \models g$.

- Suppose there is a g such that $KB \vdash g$ and $KB \not\models g$.
- Then there must be a first atom added to C that isn't true in every model of KB. Call it h. Suppose h isn't true in model I of KB.
- There must be a clause in KB of form

 $h \leftarrow b_1 \land \ldots \land b_m$

Each b_i is true in *I*. *h* is false in *I*. So this clause is false in *I*. Therefore *I* isn't a model of *KB*.

Contradiction.

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- The *C* generated at the end of the bottom-up algorithm is called a fixed point.
- Let *I* be the interpretation in which every element of the fixed point is true and every other atom is false.
- *I* is a model of *KB*.
 Proof: suppose *h* ← *b*₁ ∧ ... ∧ *b_m* in *KB* is false in *I*. Then *h* is false and each *b_i* is true in *I*. Thus *h* can be added to *C*. Contradiction to *C* being the fixed point.
- *I* is called a Minimal Model.

If $KB \models g$ then $KB \vdash g$.

- Suppose $KB \models g$. Then g is true in all models of KB.
- Thus g is true in the minimal model.
- Thus g is in the fixed point.
- Thus g is generated by the bottom up algorithm.
- Thus $KB \vdash g$.

Idea: search backward from a query to determine if it is a logical consequence of KB.

An answer clause is of the form:

 $yes \leftarrow a_1 \land a_2 \land \ldots \land a_m$

The SLD Resolution of this answer clause on atom a_i with the clause:

$$a_i \leftarrow b_1 \land \ldots \land b_p$$

is the answer clause

$$yes \leftarrow a_1 \wedge \cdots \wedge a_{i-1} \wedge b_1 \wedge \cdots \wedge b_p \wedge a_{i+1} \wedge \cdots \wedge a_m.$$

- An <u>answer</u> is an answer clause with m = 0. That is, it is the answer clause yes ← .
- A derivation of query " $q_1 \land \ldots \land q_k$ " from *KB* is a sequence of answer clauses $\gamma_0, \gamma_1, \ldots, \gamma_n$ such that
 - γ_0 is the answer clause $yes \leftarrow q_1 \land \ldots \land q_k$,
 - γ_i is obtained by resolving γ_{i-1} with a clause in KB, and
 - γ_n is an answer.

To solve the query $?q_1 \land \ldots \land q_k$:

$$ac := "yes \leftarrow q_1 \land \ldots \land q_k"$$

repeat

select atom a; from the body of ac; choose clause C from KB with a; as head; replace a; in the body of ac by the body of C until ac is an answer.

- Don't-care nondeterminism If one selection doesn't lead to a solution, there is no point trying other alternatives. select
- Don't-know nondeterminism If one choice doesn't lead to a solution, other choices may. choose

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Example: successful derivation

$$\begin{array}{lll} a \leftarrow b \wedge c. & a \leftarrow e \wedge f. & b \leftarrow f \wedge k. \\ c \leftarrow e. & d \leftarrow k. & e. \\ f \leftarrow j \wedge e. & f \leftarrow c. & j \leftarrow c. \end{array}$$

Query: ?a

γ_0 :	yes $\leftarrow a$	γ_{4} :	$yes \leftarrow e$
γ_1 :	$\textit{yes} \gets \mathbf{e} \land f$	γ_5 :	$\textit{yes} \leftarrow$
γ_2 :	yes $\leftarrow f$		
γ_3 :	yes $\leftarrow c$		

$$\begin{array}{lll} a \leftarrow b \wedge c. & a \leftarrow e \wedge f. & b \leftarrow f \wedge k. \\ c \leftarrow e. & d \leftarrow k. & e. \\ f \leftarrow j \wedge e. & f \leftarrow c. & j \leftarrow c. \end{array}$$

Query: ?a

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Search Graph for SLD Resolution



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Electrical Domain



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Representing the Electrical Environment

light h	$lit_l_1 \leftarrow light_l_1 \land live_w_0 \land ok_l_1$
light h	$\mathit{live_w_0} \leftarrow \mathit{live_w_1} \land \mathit{up_s_2}.$
down_{r2}	$\mathit{live_w_0} \leftarrow \mathit{live_w_2} \land \mathit{down_s_2}.$
$uown_s_1$.	$\mathit{live_w_1} \leftarrow \mathit{live_w_3} \land \mathit{up_s_1}.$
up_{s_2} .	$live_w_2 \leftarrow live_w_3 \land down_s_1.$
up_s ₃ .	$lit_{l_2} \leftarrow light_{l_2} \wedge live_{w_4} \wedge ok_{l_2}$.
ok_l ₁ .	$live_{w_4} \leftarrow live_{w_3} \wedge up_{s_3}$.
ok_l ₂ .	$live_p_1 \leftarrow live_w_3$.
$ok_{-}cb_{1}$.	live $w_3 \leftarrow live w_5 \land ok cb_1$.
$ok_{-}cb_{2}.$	live $p_2 \leftarrow live w_{e}$
live_outside.	live $w_c \leftarrow live w_c \land ak cho$
	live $w_{\epsilon} \leftarrow live outside$

- In the electrical domain, what should the house builder know?
- What should an occupant know?

- In the electrical domain, what should the house builder know?
- What should an occupant know?
- Users can't be expected to volunteer knowledge:
 - They don't know what information is needed.
 - They don't know what vocabulary to use.

- Users can provide observations to the system. They can answer specific queries.
- Askable atoms are those that a user should be able to observe.
- There are 3 sorts of goals in the top-down proof procedure:
 - ► Goals for which the user isn't expected to know the answer.
 - Askable atoms that may be useful in the proof.
 - Askable atoms that the user has already provided information about.

- Users can provide observations to the system. They can answer specific queries.
- Askable atoms are those that a user should be able to observe.
- There are 3 sorts of goals in the top-down proof procedure:
 - ► Goals for which the user isn't expected to know the answer.
 - Askable atoms that may be useful in the proof.
 - Askable atoms that the user has already provided information about.
- The top-down proof procedure can be modified to ask users about askable atoms they have not already provided answers for.
HOW questions can be used to ask how an atom was proved. It gives the rule used to prove the atom. You can the ask HOW an element of the body of that rules was proved.

This lets the user explore the proof.

• WHY questions can be used to ask why a question was asked. It provides the rule with the asked atom in the body. You can ask WHY the rule in the head was asked. There are four types of non-syntactic errors that can arise in rule-based systems:

An incorrect answer is produced: an atom that is false in the intended interpretation was derived.

Some answer wasn't produced: the proof failed when it should have succeeded. Some particular true atom wasn't derived.

The program gets into an infinite loop.

The system asks irrelevant questions.

- Suppose atom g was proved but is false in the intended interpretation.
- There must be a rule g ← a₁ ∧ ... ∧ a_k in the knowledge base that was used to prove g.
- Either:
 - one of the *a_i* is false in the intended interpretation or
 - all of the a_i are true in the intended interpretation.
- Incorrect answers can be debugged by only answering yes/no questions.

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If atom g is true in the intended interpretation, but could not be proved, either:

- There is no appropriate rule for g.
- There is a rule $g \leftarrow a_1 \land \ldots \land a_k$ that should have succeeded.

If atom g is true in the intended interpretation, but could not be proved, either:

- There is no appropriate rule for g.
- There is a rule $g \leftarrow a_1 \land \ldots \land a_k$ that should have succeeded.
 - One of the a_i is true in the interpretation and could not be proved.

- In the electrical domain, what if we predict that a light should be on, but observe that it isn't? What can we conclude?
- We will expand the definite clause language to include integrity constraints which are rules that imply *false*, where *false* is an atom that is false in all interpretations.
- This will allow us to make conclusions from a contradiction.
- A definite clause knowledge base is always consistent. This won't be true with the rules that imply *false*.

• An integrity constraint is a clause of the form $false \leftarrow a_1 \land \ldots \land a_k$

where the a_i are atoms and *false* is a special atom that is false in all interpretations.

• A Horn clause is either a definite clause or an integrity constraint.

- Negations can follow from a Horn clause KB.
- The negation of α , written $\neg \alpha$ is a formula that
 - is true in interpretation I if α is false in I, and
 - is false in interpretation I if α is true in I.

• Example:

$$KB = \left\{ \begin{array}{l} \text{false} \leftarrow a \land b. \\ a \leftarrow c. \\ b \leftarrow c. \end{array} \right\} \qquad KB \models \neg c.$$

- Disjunctions can follow from a Horn clause KB.
- The disjunction of α and $\beta,$ written $\alpha \lor \beta,$ is
 - true in interpretation *I* if α is true in *I* or β is true in *I* (or both are true in *I*).
 - false in interpretation I if α and β are both false in I.

• Example:

$$KB = \left\{ \begin{array}{c} false \leftarrow a \land b. \\ a \leftarrow c. \\ b \leftarrow d. \end{array} \right\} \qquad KB \models \neg c \lor \neg d.$$

- An assumable is an atom whose negation you are prepared to accept as part of a (disjunctive) answer.
- A conflict of *KB* is a set of assumables that, given *KB* imply *false*.
- A minimal conflict is a conflict such that no strict subset is also a conflict.

Example: If $\{c, d, e, f, g, h\}$ are the assumables

$$KB = \left\{ \begin{array}{l} \text{false} \leftarrow a \land b. \\ a \leftarrow c. \\ b \leftarrow d. \\ b \leftarrow e. \end{array} \right\}$$

- $\{c, d\}$ is a conflict
- $\{c, e\}$ is a conflict
- $\{c, d, e, h\}$ is a conflict

Using Conflicts for Diagnosis

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- Assume that the user is able to observe whether a light is lit or dark and whether a power outlet is dead or live.
- A light can't be both lit and dark. An outlet can't be both live and dead:

 $false \leftarrow dark_{-}l_{1} \& lit_{-}l_{1}.$ $false \leftarrow dark_{-}l_{2} \& lit_{-}l_{2}.$ $false \leftarrow dead_{-}p_{1} \& live_{-}p_{2}.$

- Assume the individual components are working correctly: *assumable ok_l*₁.
 *assumable ok_s*₂.
- Suppose switches s₁, s₂, and s₃ are all up: up_s₁. up_s₂. up_s₃.

Electrical Environment



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Representing the Electrical Environment

*light_l*₁. *light_l*₂. *up_s*₁. *up_s*₂. *up_s*₃.

live_outside.

$lit_l_1 \leftarrow light_l_1 \land live_w_0 \land ok_l_1.$
$\mathit{live}_w_0 \leftarrow \mathit{live}_w_1 \land \mathit{up}_s_2 \land \mathit{ok}_s_2.$
$\textit{live_w_0} \gets \textit{live_w_2} \land \textit{down_s_2} \land \textit{ok_s_2}.$
$\mathit{live}_w_1 \leftarrow \mathit{live}_w_3 \land up_s_1 \land ok_s_1.$
$\textit{live_w_2} \gets \textit{live_w_3} \land \textit{down_s_1} \land \textit{ok_s_1}.$
$\textit{lit}_{-l_2} \leftarrow \textit{light}_{-l_2} \land \textit{live}_{-w_4} \land \textit{ok}_{-l_2}.$
$\mathit{live_w_4} \leftarrow \mathit{live_w_3} \land \mathit{up_s_3} \land \mathit{ok_s_3}.$
$\mathit{live_p_1} \leftarrow \mathit{live_w_3}.$
$\mathit{live}_w_3 \leftarrow \mathit{live}_w_5 \land \mathit{ok}_\mathit{cb}_1.$
$live_p_2 \leftarrow live_w_6.$
$\mathit{live_w_6} \leftarrow \mathit{live_w_5} \land \mathit{ok_cb_2}.$
$\mathit{live_w_5} \leftarrow \mathit{live_outside}.$

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• If the user has observed l_1 and l_2 are both dark:

 $dark_{l_1}$. $dark_{l_2}$.

- There are two minimal conflicts: {ok_cb_1, ok_s_1, ok_s_2, ok_l_1} and {ok_cb_1, ok_s_3, ok_l_2}.
- You can derive:

 $\neg ok_cb_1 \lor \neg ok_s_1 \lor \neg ok_s_2 \lor \neg ok_l_1$ $\neg ok_cb_1 \lor \neg ok_s_3 \lor \neg ok_l_2.$

• Either *cb*₁ is broken or there is one of six double faults.

- A consistency-based diagnosis is a set of assumables that has at least one element in each conflict.
- A minimal diagnosis is a diagnosis such that no subset is also a diagnosis.
- Intuitively, one of the minimal diagnoses must hold. A diagnosis holds if all of its elements are false.
- Example: For the proceeding example there are seven minimal diagnoses: {ok_cb1}, {ok_s1, ok_s3}, {ok_s1, ok_l2}, {ok_s2, ok_s3},...

To solve the query $?q_1 \land \ldots \land q_k$:

$$ac := "yes \leftarrow q_1 \land \ldots \land q_k"$$

repeat

select atom a; from the body of ac; choose clause C from KB with a; as head; replace a; in the body of ac by the body of C until ac is an answer.

- Query is false.
- Don't select an atom that is assumable.
- Stop when all of the atoms in the body of the generalised query are assumable:
 - this is a conflict

false \leftarrow a. $a \leftarrow b \& c$. $b \leftarrow d$. $b \leftarrow e$. $c \leftarrow f$. $c \leftarrow g$. $e \leftarrow h \& w$. $e \leftarrow g$. $w \leftarrow f$. assumable d, f, g, h.

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- Conclusions are pairs (a, A), where a is an atom and A is a set of assumables that imply a.
- Initially, conclusion set $C = \{ \langle a, \{a\} \rangle : a \text{ is assumable} \}.$
- If there is a rule $h \leftarrow b_1 \land \ldots \land b_m$ such that for each b_i there is some A_i such that $\langle b_i, A_i \rangle \in C$, then $\langle h, A_1 \cup \ldots \cup A_m \rangle$ can be added to C.
- If (a, A₁) and (a, A₂) are in C, where A₁ ⊂ A₂, then (a, A₂) can be removed from C.
- If $\langle false, A_1 \rangle$ and $\langle a, A_2 \rangle$ are in *C*, where $A_1 \subseteq A_2$, then $\langle a, A_2 \rangle$ can be removed from *C*.

 $C := \{ \langle a, \{a\} \rangle : a \text{ is assumable } \};$ repeat select clause " $h \leftarrow b_1 \land \ldots \land b_m$ " in T such that $\langle b_i, A_i \rangle \in C$ for all i and there is no $\langle h, A' \rangle \in C$ or $\langle false, A' \rangle \in C$ such that $A' \subseteq A$ where $A = A_1 \cup \ldots \cup A_m$; $C := C \cup \{ \langle h, A \rangle \}$

Remove any elements of C that can now be pruned; until no more selections are possible

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Complete Knowledge Assumption

- Often you want to assume that your knowledge is complete.
- Example: you can state what switches are up and the agent can assume that the other switches are down.
- Example: assume that a database of what students are enrolled in a course is complete.
- The definite clause language is monotonic: adding clauses can't invalidate a previous conclusion.
- Under the complete knowledge assumption, the system is non-monotonic: adding clauses can invalidate a previous conclusion.

• Suppose the rules for atom a are

$$a \leftarrow b_1.$$

 \vdots
 $a \leftarrow b_n.$

equivalently $a \leftarrow b_1 \lor \ldots \lor b_n$.

• Under the Complete Knowledge Assumption, if *a* is true, one of the *b_i* must be true:

 $a \rightarrow b_1 \vee \ldots \vee b_n$.

• Under the CKA, the clauses for a mean Clark's completion: $a \leftrightarrow b_1 \lor \ldots \lor b_n$

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- Clark's completion of a knowledge base consists of the completion of every atom.
- If you have an atom *a* with no clauses, the completion is $a \leftrightarrow false$.
- You can interpret negations in the body of clauses.
 ~a means that a is false under the complete knowledge assumption

This is negation as failure.

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 $C := \{\};$ repeat either select $r \in KB$ such that r is " $h \leftarrow b_1 \land \ldots \land b_m$ " $b_i \in C$ for all *i*, and $h \notin C$; $C := C \cup \{h\}$ or select h such that for every rule " $h \leftarrow b_1 \land \ldots \land b_m$ " $\in KB$ either for some $b_i, \sim b_i \in C$ or some $b_i = \sim g$ and $g \in C$ $C := C \cup \{\sim h\}$ until no more selections are possible

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$$p \leftarrow q \land \sim r.$$

$$p \leftarrow s.$$

$$q \leftarrow \sim s.$$

$$r \leftarrow \sim t.$$

$$t.$$

$$s \leftarrow w.$$

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Top-Down negation as failure proof procedure

- If the proof for *a* fails, you can conclude $\sim a$.
- Failure can be defined recursively: Suppose you have rules for atom *a*:

$$a \leftarrow b_1$$

:
 $a \leftarrow b_n$

If each body b_i fails, a fails.

A body fails if one of the conjuncts in the body fails. Note that you need *finite* failure. Example $p \leftarrow p$.

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Often we want our agents to make assumptions rather than doing deduction from their knowledge. For example:

- In abduction an agent makes assumptions to explain observations. For example, it hypothesizes what could be wrong with a system to produce the observed symptoms.
- In default reasoning an agent makes assumptions of normality to make predictions. For example, the delivery robot may want to assume Mary is in her office, even if it isn't always true.

Two different tasks use assumption-based reasoning:

- Design The aim is to design an artifact or plan. The designer can select whichever design they like that satisfies the design criteria.
- Recognition The aim is to find out what is true based on observations. If there are a number of possibilities, the recognizer can't select the one they like best. The underlying reality is fixed; the aim is to find out what it is.

Compare: Recognizing a disease with designing a treatment. Designing a meeting time with determining when it is. The assumption-based framework is defined in terms of two sets of formulae:

- F is a set of closed formula called the facts.
 These are formulae that are given as true in the world.
 We assume F are Horn clauses.
- *H* is a set of formulae called the possible hypotheses or assumables. Ground instance of the possible hypotheses can be assumed if consistent.

- A scenario of (F, H) is a set D of ground instances of elements of H such that F ∪ D is satisfiable.
- An explanation of g from $\langle F, H \rangle$ is a scenario that, together with F, implies g.

D is an explanation of *g* if $F \cup D \models g$ and $F \cup D \not\models false$. A minimal explanation is an explanation such that no strict subset is also an explanation.

An extension of ⟨F, H⟩ is the set of logical consequences of F and a maximal scenario of ⟨F, H⟩.

• $\{e, m, n\}$ is a scenario. $a \leftarrow b \land c$. $b \leftarrow e$. • $\{e, g, m\}$ is not a scenario. $b \leftarrow h$. • $\{h, m\}$ is an explanation for a. $c \leftarrow g$. • $\{e, h, m\}$ is an explanation for a. $c \leftarrow f$. • $\{e, g, h, m\}$ isn't an explanation. $d \leftarrow g$. false $\leftarrow e \land d$. • $\{e, h, m, n\}$ is a maximal scenario. $f \leftarrow h \wedge m$. • $\{h, g, m, n\}$ is a maximal scenario. assumable e, h, g, m, n.

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There are two strategies for using the assumption-based framework:

- Default reasoning Where the truth of g is unknown and is to be determined.
 An explanation for g corresponds to an argument for g.
- Abduction Where g is given, and we are interested in explaining it. g could be an observation in a recognition task or a design goal in a design task.

Give observations, we typically do abduction, then default reasoning to find consequences.

To find assumables to imply the query $?q_1 \land \ldots \land q_k$:

$$ac := "yes \leftarrow q_1 \land \ldots \land q_k"$$

repeat

select non-assumable atom a; from the body of ac; choose clause C from KB with a; as head; replace a; in the body of ac by the body of C until all atoms in the body of ac are assumable.

To find an explanation of query $?q_1 \land \ldots \land q_k$:

- find assumables to imply $?q_1 \land \ldots \land q_k$
- ensure that no subset of the assumables found implies false

- When giving information, we don't want to enumerate all of the exceptions, even if we could think of them all.
- In default reasoning, we specify general knowledge and modularly add exceptions. The general knowledge is used for cases we don't know are exceptional.
- Classical logic is monotonic: If g logically follows from A, it also follows from any superset of A.
- Default reasoning is nonmonotonic: When we add that something is exceptional, we can't conclude what we could before.
Default reasoning can be modeled using

- *H* is normality assumptions
- F states what follows from the assumptions

An explanation of g gives an argument for g.

A reader of newsgroups may have a default: "Articles about AI are generally interesting".

 $H = \{int_ai\},\$

where int_ai means X is interesting if it is about AI. With facts:

```
interesting \leftarrow about_ai \land int_ai.
about_ai.
```

{*int_ai*} is an explanation for *interesting*.

We can have exceptions to defaults:

 $false \leftarrow interesting \land uninteresting.$

Suppose an article is about AI but is uninteresting:

```
interesting \leftarrow about_ai \land int_ai.
about_ai.
uninteresting.
```

We cannot explain *interesting* even though everything we know about the previous we also know about this case.

Exceptions to defaults



"Articles about formal logic are about AI." "Articles about formal logic are uninteresting." "Articles about machine learning are about AI."

```
about_ai ← about_fl.
```

```
uninteresting \leftarrow about_fl.
```

about_ai ← about_ml.

interesting \leftarrow about_ai \land int_ai.

 $\mathit{false} \leftarrow \mathit{interesting} \land \mathit{uninteresting}.$

false \leftarrow *intro_question* \land *interesting*.

Given *about_fl*, is there explanation for *interesting*? Given *about_ml*, is there explanation for *interesting*?

Exceptions to Defaults



Formal logic is uninteresting by default



Suppose formal logic articles aren't interesting by default:

 $H = \{unint_fl, int_ai\}$

The corresponding facts are:

 $\begin{array}{l} \textit{interesting} \leftarrow \textit{about_ai} \land \textit{int_ai.} \\ \textit{about_ai} \leftarrow \textit{about_fl.} \\ \textit{uninteresting} \leftarrow \textit{about_fl} \land \textit{unint_fl.} \\ \textit{false} \leftarrow \textit{interesting} \land \textit{uninteresting.} \\ \textit{about_fl.} \end{array}$

Does *uninteresting* have an explanation? Does *interesting* have an explanation?

- For an article about formal logic, the argument "it is interesting because it is about AI" shouldn't be applicable.
- This is an instance of preference for more specific defaults.
- Arguments that articles about formal logic are interesting because they are about AI can be defeated by adding:

 $false \leftarrow about_fl \land int_ai.$

This is known as a cancellation rule.

• We can no longer explain *interesting*.

Diagram of the Default Example



- What if incompatible goals can be explained and there are no cancellation rules applicable?
 What should we predict?
- For example: what if introductory questions are uninteresting, by default?
- This is the multiple extension problem .
- Recall: an extension of $\langle F, H \rangle$ is the set of logical consequences of F and a maximal scenario of $\langle F, H \rangle$.

Competing Arguments



- We predict g if g is in all extensions of $\langle F, H \rangle$.
- Suppose g isn't in extension E. As far as we are concerned E could be the correct view of the world.
 So we shouldn't predict g.
- If g is in all extensions, then no matter which extension turns out to be true, we still have g true.
- Thus g is predicted even if an adversary gets to select assumptions, as long as the adversary is forced to select something. You do not predict g if the adversary can pick assumptions from which g can't be explained.

Recall: logical consequence is defined as truth in all models. We can define default prediction as truth in all minimal models. Suppose M_1 and M_2 are models of the facts. $M_1 <_H M_2$ if the hypotheses violated by M_1 are a strict subset of the hypotheses violated by M_2 . That is:

 ${h \in H' : h \text{ is false in } M_1} \subset {h \in H' : h \text{ is false in } M_2}$

where H' is the set of ground instances of elements of H.

- *M* is a minimal model of *F* with respect to *H* if *M* is a model of *F* and there is no model M_1 of *F* such that $M_1 <_H M$.
- g is minimally entailed from $\langle F, H \rangle$ if g is true in all minimal models of F with respect to H.
- Theorem: g is minimally entailed from ⟨F, H⟩ if and only if g is in all extensions of ⟨F, H⟩.

Much reasoning in AI can be seen as evidential reasoning, (observations to a theory) followed by causal reasoning (theory to predictions).

- Diagnosis Given symptoms, evidential reasoning leads to hypotheses about diseases or faults, these lead via causal reasoning to predictions that can be tested.
- Robotics Given perception, evidential reasoning can lead us to hypothesize what is in the world, that leads via causal reasoning to actions that can be executed.

To combine evidential and causal reasoning, you can either

- Axiomatize from causes to their effects and
 - use abduction for evidential reasoning
 - use default reasoning for causal reasoning
- Axiomatize both
 - effects \rightarrow possible causes (for evidential reasoning)
 - causes → effects (for causal reasoning)

use a single reasoning mechanism, such as default reasoning.

• Representation:

- Axiomatize causally using rules.
- Have normality assumptions (defaults) for prediction
- other assumptions to explain observations
- Reasoning:
 - given an observation, use all assumptions to explain observation (find base causes)
 - use normality assumptions to predict from base causes explanations.



Why is the infobot trying another information source? (Arrows are implications or defaults. Sources are assumable.)

error_message \leftarrow data_absent \land da_em. another source tried \leftarrow data absent \land da ast another_source_tried \leftarrow data_inadequate \land di_ast. data absent \leftarrow file removed \land fr da. data absent \leftarrow link down \wedge ld da. default da_em, da_ast, di_ast, fr_da, ld_da. assumable *file_removed*. assumable link_down. assumable *data_inadequate*.

Example: fire alarm



assumable *tampering*.

assumable fire.

 $alarm \leftarrow tampering \land tampering_caused_alarm.$

 $alarm \leftarrow fire \land fire_caused_alarm.$

default tampering_caused_alarm.

default fire_caused_alarm.

 $smoke \leftarrow fire \land fire_caused_smoke.$

default *fire_caused_smoke*.

leaving \leftarrow *alarm* \land *alarm*_*caused*_*leaving*.

default *alarm_caused_leaving*.

 $report \leftarrow leaving \land leaving_caused_report.$

default *leaving_caused_report*.

- If we observe *report* there are two minimal explanations:
 - one with tampering
 - one with fire
- If we observed just *smoke* there is one explanation (containing *fire*). This explanation makes no predictions about tampering.
- If we had observed *report* \land *smoke*, there is one minimal explanation, (containing fire).
 - The smoke explains away the tampering. There is no need to hypothesise tampering to explain report.